

Branching-time logic CTL

Syntax

$\varphi ::= \dots$

$\underline{AX}\varphi \mid \underline{EX}\varphi \mid \underline{AG}\varphi \mid \underline{AF}\varphi$
 $\underline{EG}\varphi \mid \underline{EF}\varphi \mid \underline{A}[\varphi \cup \varphi] \mid \underline{E}[\varphi \cup \varphi]$

Convention: connectives of CTL
bind in the following
order

unary: ($\neg$, AG , EG , AF , EF ,
 AX , EX)

then ($\wedge$, $\vee$)

finally ($\rightarrow$, AU , EU)

Example: WFF?

$AG (q \rightarrow EGr) \checkmark$

$AG q \rightarrow EGr \checkmark$

$EF (EGp) \checkmark$

$EF (rUq) \times$

$A [rUq \vee pUq] \times$

$A EF r) \times$

$A [(rvq)U(pvq)] \checkmark$

$A [r \vee (qU r) \vee q] \times$

$AU?$

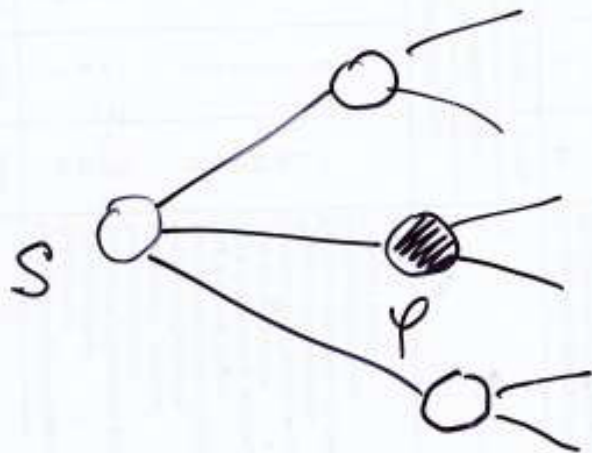
$A [\psi U \psi]$

Semantics

$M, s \models \text{EX } \varphi$ iff

for some s_1 s.t. $s \rightarrow s_1$

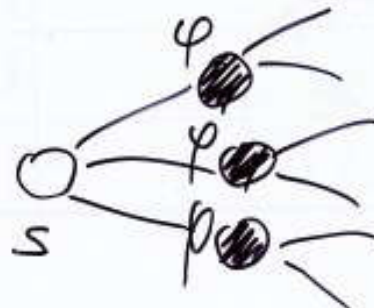
$M, s_1 \models \varphi$



$M, s \models \text{AX } \varphi$ iff

for all s_1 s.t. $s \rightarrow s_1$

$M, s_1 \models \varphi$



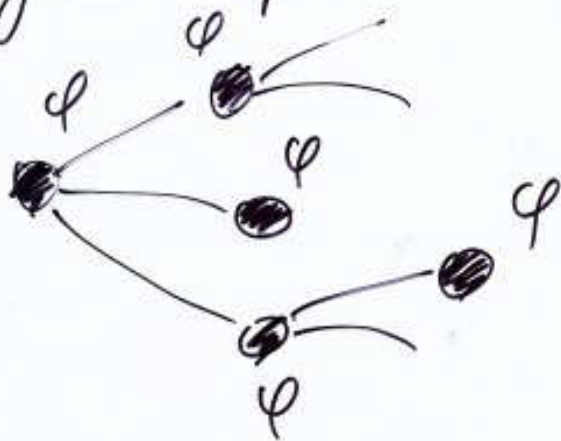
$M, s \models AG \varphi$ iff for all

paths $s \rightarrow s_1 \rightarrow s_2 \rightarrow s_3 \rightarrow \dots$

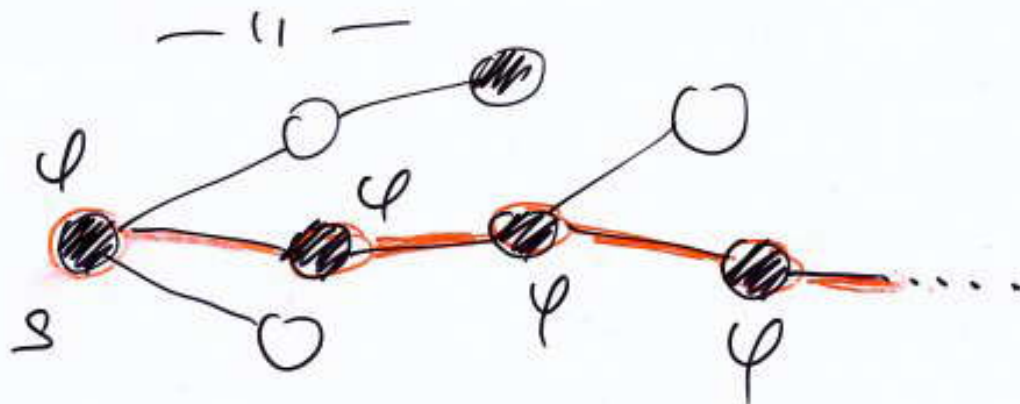
where $s = s_1$

and for all states s_i

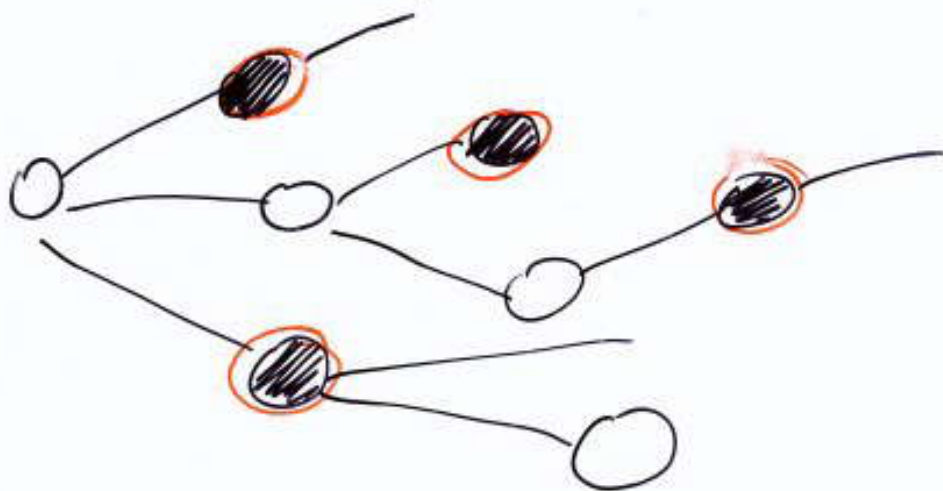
along the path, $M, s_i \models \varphi$



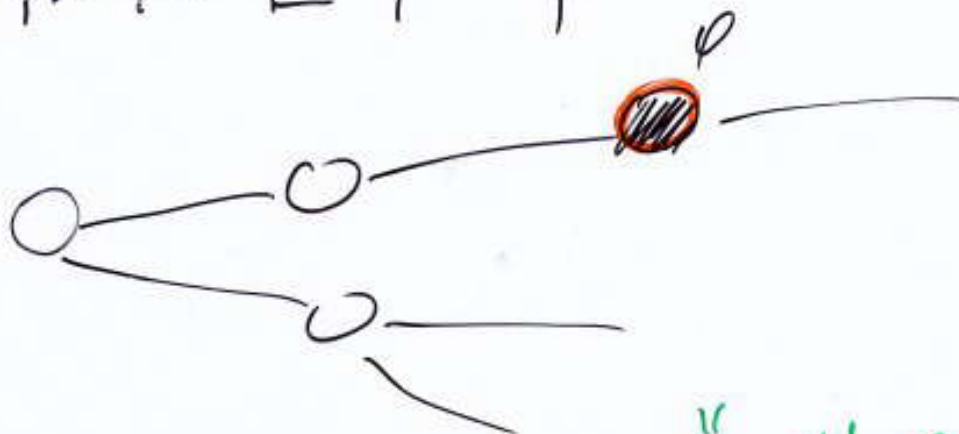
$M, s \models EG \varphi$ iff exists



$$M, s \models AF \varphi$$



$$M, s \models EF \varphi$$



In particular,



(for both AF, EF)

"path quantified"
A, E

"state quantified"
G, F

$$M, s \models A [\varphi_1 \cup \varphi_2] \text{ iff}$$

In every path,



In particular



$$M, s \models E [\varphi_1 \cup \varphi_2] \text{ iff}$$

In some path,



CTL examples

$$M, s_0 \models AX(AFr) \quad \checkmark$$

$$M, s_0 \models AX(AGr) \quad \times$$

$$M, s_0 \models EX(AGr) \quad \checkmark$$

$$M, s_0 \models q \rightarrow EXr \quad \checkmark$$

$$M, s_0 \models (p \wedge q) \wedge AX(A[pUr])$$

$$M, s_0 \models AGp \rightarrow p \quad \checkmark \quad \checkmark$$

$$M, s_0 \models EX(AGr) \quad \checkmark$$

$$M, s_0 \models \underline{AGE}[pUr] \quad \checkmark$$

LTL is more expressive than CTL

Can describe paths with several conditions along the same path, e.g.

"if π has p then π has q as well"

$$F p \rightarrow F q$$

CTL is more expressive than LTL

Can represent branching time properties, e.g. "for every state satisfying p there is a successor satisfying q "

Can we combine the advantages
of both?

Yes! CTL*!

Idea: drop the CTL constraint
that each of (x, u, F, G)
must be associated with
a unique path quantifier

Can write:

$$A \models (p \text{ } u \text{ } r) \vee (q \text{ } u \text{ } r) \\ \neq A \models (p \vee q) \text{ } u \text{ } r$$

$$E \models G E p \\ \neq E G E F p$$

CTL*

Syntax:

- State formulas (evaluated in states,

$$\varphi ::= T \mid p \mid (\neg \varphi) \mid (\varphi \wedge \varphi) \mid (\varphi \vee \varphi) \mid$$

$$A[\alpha] \mid E[\alpha]$$

where α is a path formula

- Path formulas (evaluated ^{along} paths)

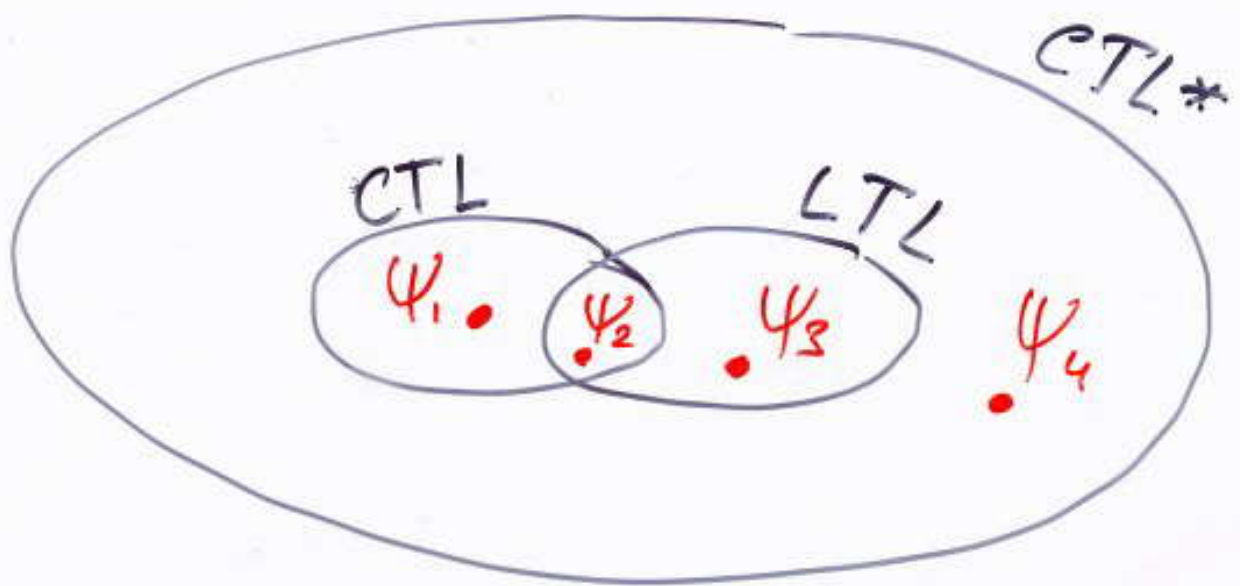
$$\alpha ::= \varphi \mid (\neg \alpha) \mid (\overset{\vee}{\alpha} \wedge \alpha) \mid (\alpha \vee \alpha) \mid$$

$$(G\alpha) \mid (F\alpha) \mid (X\alpha),$$

where φ is a state formula

(mutually recursive def.)

LTL and CTL as subsets of CTL*



In CTL, not in LTL $\psi_1 = AG EF p$

In LTL and in CTL $\psi_2 = G(p \rightarrow Fq)$
 $\checkmark \stackrel{?}{=} AG(p \rightarrow AFq)$

In LTL, not in CTL $\psi_3 = A[G(Fp) \rightarrow Fq]$

Emerson
(hand)

inf. of $p \rightarrow$ an occ. of q

In CTL*, not in CTL
 not in LTL

$\psi_4 = E[GFp]$

$AG(n_i \rightarrow EX t_i)$ is not expressible
in LTL

Proof: Sup. it is expr. by ψ ,

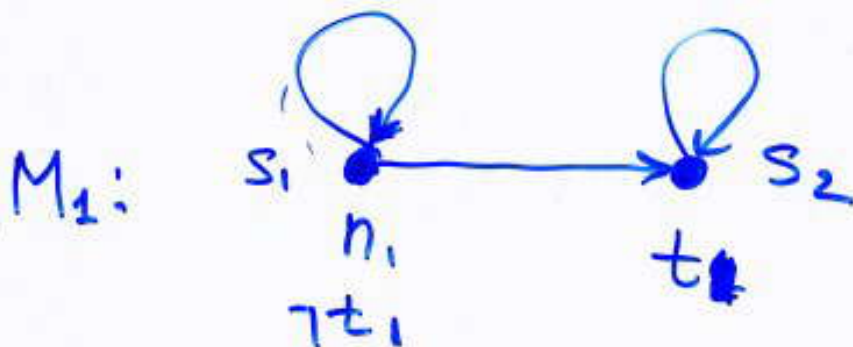
then $AG(n_i \rightarrow EX t_i) \equiv A[\overset{\text{LTL}}{\downarrow} \psi]$
(in CTL*)

$\forall M \forall s$

$M, s \models AG(n_i \rightarrow EX t_i)$

iff

$M, s \models A[\psi]$



Since $M_1, s_1 \models \boxed{AG(n_1 \rightarrow EX t_1)}$,

we have $M_1, s_1 \models A[\psi]$

Consider :



Since $M_1, s_1 \models A[\psi]$, we must have $M_2, s_1 \models A[\psi]$.

But $M_2, s_1 \not\models AG(n_1 \rightarrow EX t_1)$ / contradiction.