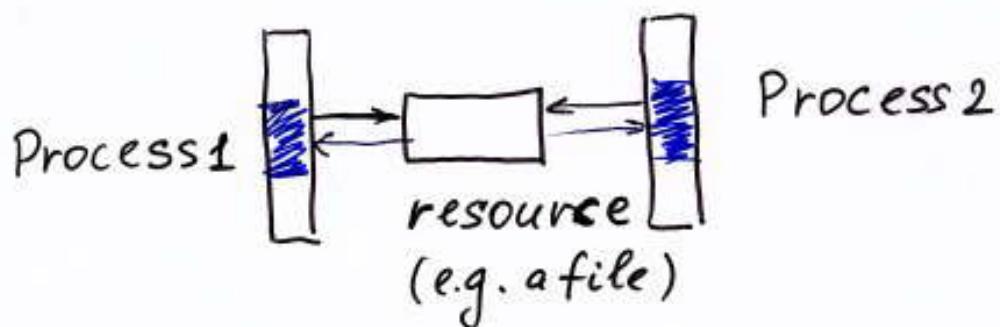


Mutual Exclusion



Critical sections of code
include all the access to the
shared resource

(only one process can be in its critical
section at a time)

Task: find a protocol for determining
which process is allowed
to enter its critical section
at which time

The protocol must have
the following properties :

Safety: only one process is
in its critical section at a time

Problem: a protocol, where none of the processes
ever enters its critical section is safe!
also, need:

Liveness: Whenever any process
wants to enter its critical section,
it will eventually be permitted to do so

non-blocking: A process can always
request to enter its critical section
(when in non-critical one)

no strict sequencing: Processes
need not enter their
critical section in strict sequence

(access of Process 1 and access of Process 2
to their critical sections don't have
to alternate.)

C₁ C₁ C₁ C₂ C₂ C₁ can be after C₁

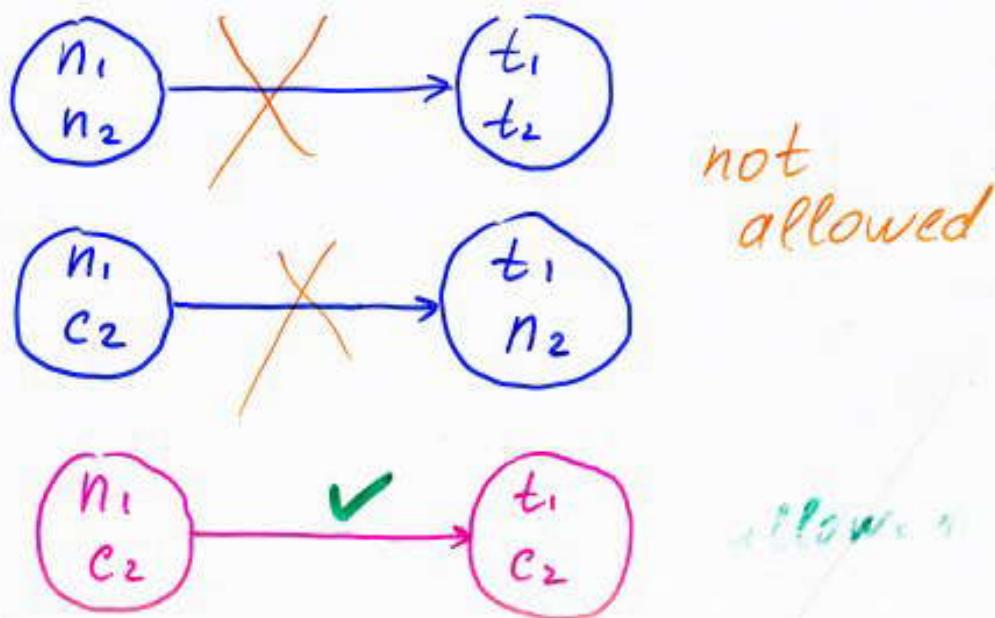
n_i : process i is in its non-critical state

t_i : process i is trying to enter its critical state

c_i : process i is in its critical state

$$n_i \rightarrow t_i \rightarrow c_i \rightarrow n_i \rightarrow t_i \rightarrow c_i \rightarrow n_i \dots$$

only one process can make a transition (say, from n to t) at a time



| LTL | CTL |
|----------------------------|--------------------------------------------|
| Safety | |
| $G \neg(c_1 \wedge c_2)$ | $\text{AG} \neg(c_1 \wedge c_2)$ |
| Liveness | |
| $G(t_1 \rightarrow F c_1)$ | $\text{AG}(t_1 \rightarrow \text{AF} c_1)$ |
| $G(t_2 \rightarrow F c_2)$ | $\text{AG}(t_2 \rightarrow \text{AF} c_2)$ |
| Non-blocking | |
| — | $\text{AG}(n_1 \rightarrow \text{EX})$ |
| | $\text{AG}(n_2 \rightarrow \text{EX} t_2)$ |

For the first modelling attempt:

Safety: ✓

Liveness: X because

there is a path, where t_1 is true in a state, but from that state on C_0 is false.

$s_0 \rightarrow s_1 \rightarrow s_3 \rightarrow s_7 \rightarrow \underbrace{s_1 \rightarrow s_3 \rightarrow s_7 \rightarrow \dots}_{\text{loop}}$

(similar for the second process)

non-blocking: ✓

for every state sat. n_1 , there is a successor sat. t_1

(similar for the second process)

No strict sequencing: ✓

there is a path where

$\dots \underbrace{c_2 c_2 c_2}_{C_2} \rightsquigarrow \underbrace{c_1 c_1 c_1 \dots c_4}_{C_1} \rightsquigarrow \underbrace{c_2 c_2 c_2}_{C_2} \rightsquigarrow \underbrace{c_1 c_1}_{C_1} \rightsquigarrow \underbrace{c_2 c_2 c_2}_{C_2}$

such alternation does not occur
(for each process)